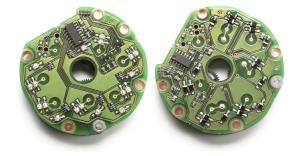
# AEAS-84AD

# 14/12 Bit Multi-turn Encoder Module



# **Data Sheet**



# **General Description**

The AEAS-84AD provides all functions as an optoelectronicmechanical unit in order to implement with AEAS-7000 an absolute multi-turn encoder with a combine capacity of up to 30 bits.

The unit consists of an IR-LED circuit board, a phototransistor (PT) circuit board, and 6 or 7 code wheels arranged in between the PCBs.

# **Specifications**

The multi-turn unit is available in the following versions:

- 12-bit solid shaft
- 14-bit solid shaft

# Applications

- · Major component of Multi-turn housed encoder
- Cost effective solution for direct integration into OE systems
- Linear positioning system

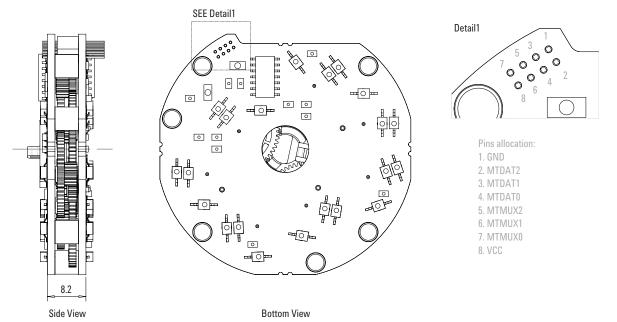
### Features

- 16384 (14bits) and 4096 (12bits) revolution count versions
- Optical, absolute multi-turn assembly with max. Ø55 mm and typical height 11.9 mm.
- Operating temperatures of -40°C to +85°C
- Mechanical coupling by means of gearwheels with module of 0.3
- Operating speeds up to 12,000 rpm
- A 2x4-pole pin strip for power supply and signals
- 5V +/-10% power supply with low power consumption
- Code wheel-like multiplexing of the digital position data

## **Benefits**

- No battery or capacitor required for number of revolution counting during power failure
- Immediate position detection on power up

## Pinning



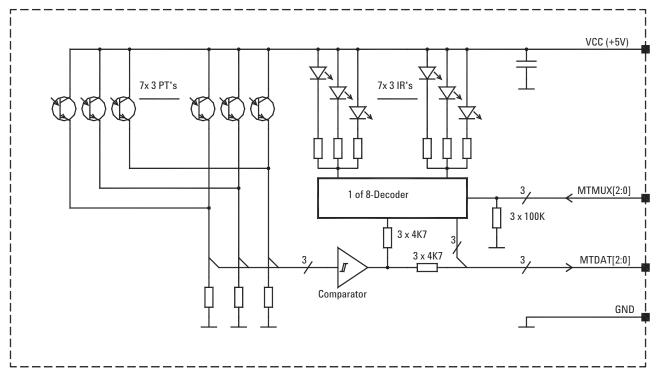
Note: 3<sup>rd</sup> angle viewing

Example of matching connector: MPE GARRY 521 Series, No. BL21-43GGG-008

Figure 1. Pin Configuration

#### **Block Diagram and Detailed Description**

In the following descriptions, the I/O pins are enclosed by a box, e.g., MTMUX[2:0].





#### **Multiplexing and Position Data**

Each of the 1:4 reduced 7 code wheels generates a 3-bit code, from which the 14-bit Gray code can be generated as position data through V-bit processing.

The 3-bit code is identical electrically for all code wheels, only the projection on the mechanical angle (the revolutions) is different according to the 1:4 divisions.

The code and the data bits and V-bits to be generated are shown in the following diagram for the code wheel 1:

The 3-bit codes of the code wheels 1 to 7 are output on MTDAT[2:0] de-multiplexed with MTMUX[2:0]. Here, the binary value on MTMUX[2:0] corresponds to the code-wheel number (1 = code wheel 1, 2 = code wheel 2, etc.). The configuration is displayed with the value "0."

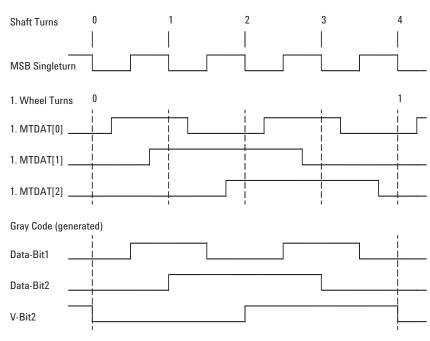


Figure 3. Multiplexing Diagram for gear wheel 1

The following table shows the assignments:

#### Table 1. Demultiplexing Diagram for all gear wheels

Bin/Dec MTMUX[2:0]	MTDAT[2]	MTDAT[1]	MTDAT[0]
001 / 1	3-bit code wheel 1		
010/2	3-bit code wheel 2		
to	to		
111/7	3-bit code wheel 7		
000 / 0	always 1	0 = 12 bit 1 = 14 bit	1 = MU1xSS

#### **Gray code-generation**

For the readout schematic of the multi-turn code gears, i.e. with the user's micro-controller, there must be a logical replication of the V-bit multiplexers. This can be done by a bit manipulation or by look up tables. Care needs to be taken with the real time readout conditions.

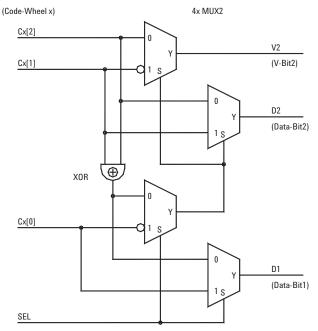
The procedure is as follows :

- 1. The 3 bits (MTDAT[2:0] of each gear (C1[2:0] bits C7[2:0]) are continuously de-multiplexed. Thus there are maximal 3bits x 7gears = 21Bit AEAS-84AD-Data in parallel.
- 2. Synchronous to the readout of the AEAS-7000 sensor, those AEAS-84AD bits (depending on the MSB bit (1.SELbit) of the AEAS-7000) needs to be complemented to the complete Gray code word (cascading).
- 3. The bit change of the complete Gray code will be synchronized by the AEAS-7000 and thus electronically eliminating gear play.

The logic diagram for ONE gear is shown in the following diagram (V-bit-Multiplexer), Figure 4.

#### Logic Diagram

From MTDAT-Demux



## **Truth Table**

SEL	Cx[0]	Cx[1]	Cx[2]	D1	D2	V2
0	0	0	0	0	0	0
0	1	0	0	0	0	0
1	1	0	0	1	0	0
1	1	1	0	1	0	0
0	1	1	0	1	1	0
0	0	1	0	1	1	0
1	0	1	0	0	1	0
1	0	1	1	0	1	0
0	0	1	1	0	1	1
0	1	1	1	0	1	1
1	1	1	1	1	1	1
1	1	0	1	1	1	1
0	1	0	1	1	0	1
0	0	0	1	1	0	1
1	0	0	1	0	0	1
1	0	0	0	0	0	1

Figure 4. Logic Diagram and Truth Table for one of the gear

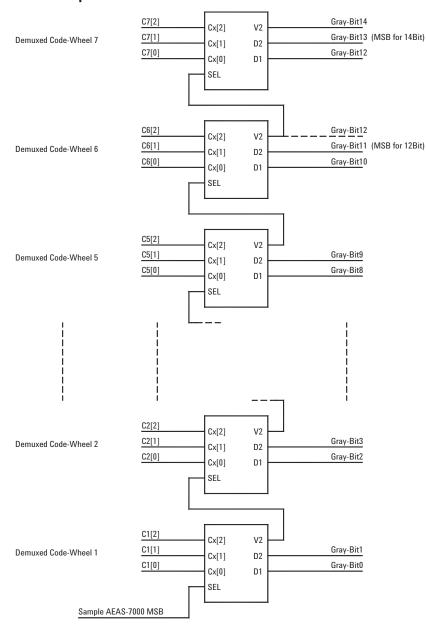
The following diagram shows the cascading of the V-bit-Multiplexer of all gears. The outputs are the 14bits Gray code in parallel.

The MSB of the complete code is dependant on the total resolution of the system. It can be used in steps of 2 bits (14Bit,12Bit,...etc). Unused higher bits should be masked to logical zero.

With the data-multiplexer IC version of the multi-turn encoder module, the data multiplexer IC will perform the complete driving and data processing of the encoder units while maintaining all time constraints. There is an IC available to combine both the AEAx-7x00 13/16-bit single turn component and the AEAx- 84AD 12/14bit multiturn module into one-single powerful multiturn absolute encoder. This one-stop solution enables the design of a high-end absolute encoder with minimum component count at integration level. Figure 6 shows an application example of integration of single-turn absolute encoder and multiturn module using MUIC.

#### Note:

To simplify the synchronization with singleturn absolute encoder(e.g. AEAS-7000), the total solution has been embedded into a single chip - MUIC. Please refer to the Ordering Information for this device.



#### V-Bit-Multiplexer-Cascade

Figure 5. The cascading of V-bit-Multiplexer of all gear wheels

#### **Application Example of Multiturn Absolute Encoder**

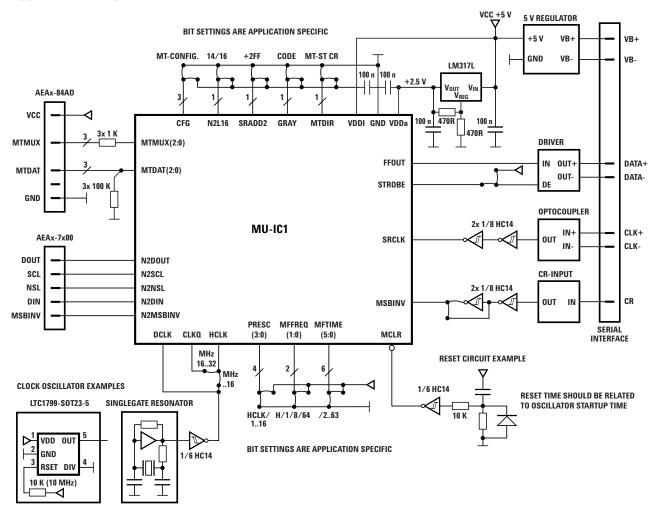


Figure 6. Application example of integration of single-turn absolute encoder module and multiturn module using MUIC.

# **Electrical Specifications**

#### **Absolute Maximum Ratings**

Symbol	Parameter	Limits	Units
VCC	DC Supply Voltage	-0.3 to +6.0	V
Vi	Input Voltage	-0.5 to +5.5	V
Vo	Output Voltage	-0.5 to +VCC +0.5	V
%RH	Moisture Level (Non-Condensing)	85	%
T <sub>stg</sub>	Storage Temperature	-40 to +100	°C

Note : This device meets the ESD ratings of the IEC61000-4-2 HBM Level 4 (8KV)

### **Recommended Operating Conditions**

Symbol	Parameter	Values	Units
VCC	DC Supply Voltage	+4.5 / +5.0 / +5.5	V
T <sub>amb</sub>	Ambient Temperature	-40 to +85	°C
t <sub>DMUXRD</sub>	Delay Multiplex Read	64	μs
S <sub>RPM</sub>	Encoder Shaft r.p.m	max 12,000	1/min

## **DC Characteristics**

 $VCC = 4.5 \text{ to } 5.5 \text{ V} / T_{amb} = -40 \text{ to } +85^{\circ}C$ 

				Values		
Symbol	Parameter		Min	Тур.	Мах	Units
V <sub>OH</sub>	MTDAT[2:0] Output High Voltage (10K Pull-up)	I <sub>OH</sub> = -50μA	4.0			V
V <sub>OL</sub>	MTDAT[2:0] Output Low Voltage (4K7 Series-R)	I <sub>OL</sub> = 50μA			0.4	V
V <sub>IH</sub>	Input High Voltage	VCC=4.5V VCC=5.5V	3.2 3.9			V
VIL	Input Low Voltage				0.8	V
I <sub>IL</sub> / I <sub>IH</sub>	MTMUX[2:0] Input Current., VIN=VCC or 0V	100K Pull-down	-10		100	μΑ
I <sub>CC</sub>	VCC Supply Current			10	20	mA

# **Timing Characteristics**

VCC= 4.5 to  $5.5V / T_{amb} = -40$  to  $+85^{\circ}C$ 

			Values		
Symbol	Parameter	Min	Тур	Мах	Units
t <sub>R</sub> / t <sub>F</sub>	Input Transition Rise-/Fall-Time 0.8V / 3.0V			500	ns
t <sub>DMUXRD</sub>	Delay Multiplex Read			57	μs
S <sub>RPM</sub>	Encoder Shaft r.p.m			12K	1/min
	old value new value				
	t DMUXRI	כ			
 MTDAT[2:0] 	C	old value		new val	ue

#### **Application Note**

The encoder is mechanically fixed by means of holes in adapters, which accommodate M3 threads. The encoder has 2 adapters for attaching in a 3 x 120° and 4 x 90° arrangement (for details see the mechanical drawings in the following page).

The mechanical coupling of the encoder shaft is realised by means of gearwheels with a module of 0.3, 14 teeth.

> Plastic plug is removed upon integration with

The zero positions of the coupling wheels are locked with a plastic plug for alignment to the AEAS-7000, with the coupling wheel being able to compensate for an angle error of about  $+/-7^{\circ}$ .

The electrical connection is realized by means of a 2x4 pin strip (1.27mm pitch), which is plugged into a corresponding female connector.

The encoder is attached with a plastic plug that locks the absolute zero position. During the mating of the gearwheel and the encoder coupling wheel it may be necessary to align the teeth of the gears for proper matching. The plastic plug can be removed upon integration with the gearwheel.

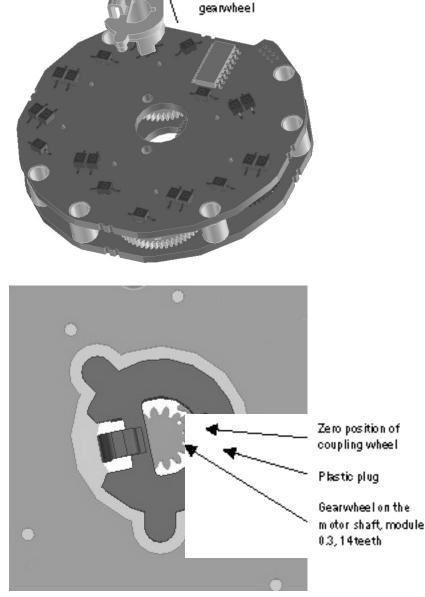
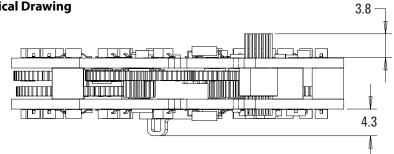
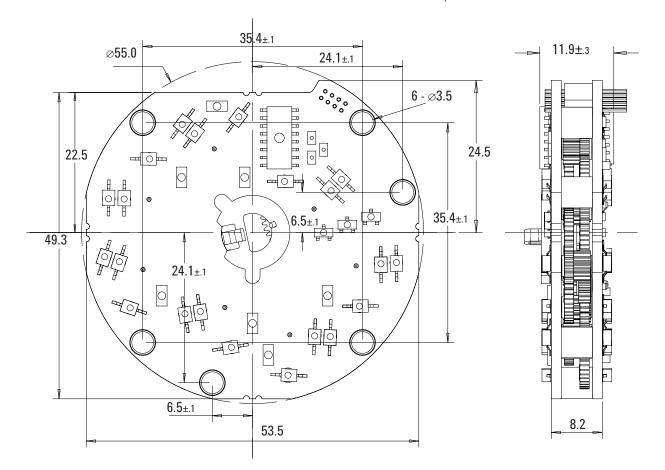


Figure 7. Mechanical coupling with Multiturn Encoder Module

## **Mechanical Drawing**





(Dimensions are in millimeters)

Figure 8. Package dimensions

## **Ordering Information**

AEAS-84AD-LBSC0	multi-turn, solid shaft, serial, 12 bit
AEAS-84AD-LBSF0	multi-turn, solid shaft, serial, 14 bit

## Ordering information for MUIC:

- MUIC1-V0 leaded, industrial temperature range +85°C
- MUIC1-V0-X79 lead-free, industrial temperature range +85°C
- Note: The manufacturer contact for the above MUIC part numbers is as follows:

OPTOLAB Microsystems AG Konrad-Zuse-Str.14 DE-99099 Erfurt / Germany Phone: +49-361-55144-0 Fax: +49-361-55144-50

For product information and a complete list of distributors, please go to our web site: www.avagotech.com

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