EMC-OPTIMIZED HIGH SPEED CAN TRANSCEIVER

FEATURES

- Qualified for Automotive Applications
- Improved Drop-In Replacement for TJA1050
- Meets or Exceeds the Requirements of ISO 11898-2
- GIFT/ICT Compliant
- ESD Protection up to ±12 kV (Human-Body Model) on Bus Pins
- High Electromagnetic Compliance (EMC)
- Bus-Fault Protection of –27 V to 40 V
- Dominant Time-Out Function
- Thermal Shutdown Protection
- Power-Up/Down Glitch-Free Bus Inputs and Outputs
  - High Input Impedance With Low V_{CC}
  - Monotonic Outputs During Power Cycling

APPLICATIONS

- GMW3122 Dual-Wire CAN Physical Layer
- SAE J2284 High-Speed CAN for Automotive Applications
- SAE J1939 Standard Data Bus Interface
- ISO 11783 Standard Data Bus Interface
- NMEA 2000 Standard Data Bus Interface

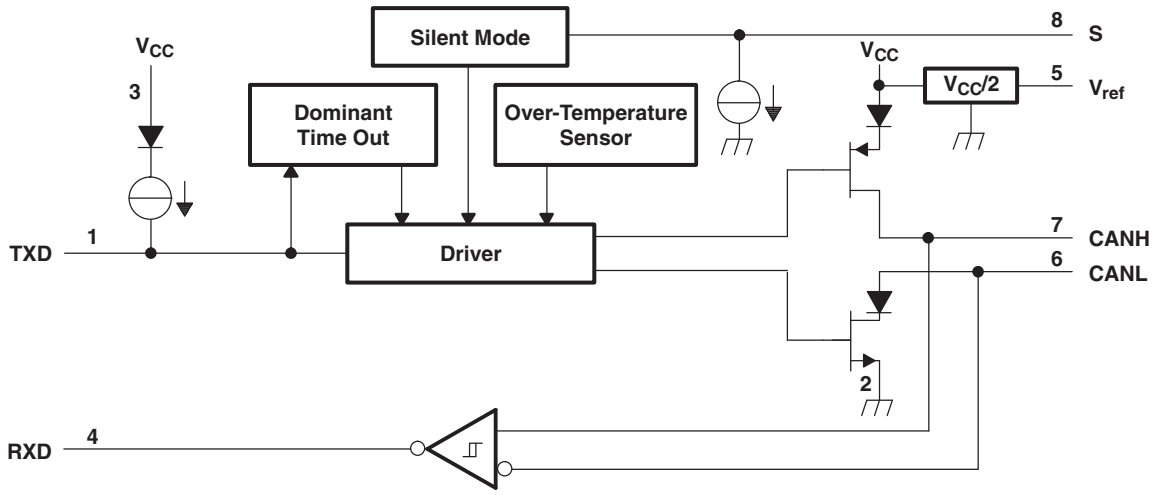
DESCRIPTION

The SN65HVD1050A meets or exceeds the specifications of the ISO 11898 standard for use in applications employing a Controller Area Network (CAN). The device is qualified for use in automotive applications.

As a CAN transceiver, this device provides differential transmit capability to the bus and differential receive capability to a CAN controller at signaling rates up to 1 megabit per second (Mbps)(1).

(1) The signaling rate of a line is the number of voltage transitions that are made per second expressed in the units bps (bits per second).

FUNCTION BLOCK DIAGRAM



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

DESCRIPTION (CONTINUED)

Designed for operation is especially harsh environments, the SN65HVD1050A features cross-wire, over-voltage, and loss of ground protection from –27 V to 40 V, over-temperature protection, a –12-V to 12-V common-mode range, and withstands voltage transients according to ISO 7637.

Pin 8 provides for two different modes of operation: high-speed or silent mode. The high-speed mode of operation is selected by connecting S (pin 8) to ground.

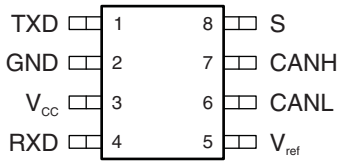
If a high logic level is applied to the S pin of the SN65HVD1050A, the device enters a listen-only silent mode during which the driver is switched off while the receiver remains fully functional.

In silent mode, all bus activity is passed by the receiver output to the local protocol controller. When data transmission is required the local protocol controller must transition the device to high speed mode by placing a logic low on the S pin to resume full operation.

A dominant time-out circuit in the SN65HVD1050A prevents the driver from blocking network communication with a hardware or software failure. The time-out circuit is triggered by a falling edge on TXD (pin 1). If no rising edge is seen before the time-out constant of the circuit expires, the driver is disabled. The circuit is then reset by the next rising edge on TXD.

V_{ref} (pin 5) is available as a $V_{CC}/2$ voltage reference.

D PACKAGE
(TOP VIEW)



ORDERING INFORMATION(1)

PART NUMBER	PACKAGE(2)	MARKED AS	ORDERING NUMBER
SN65HVD1050A-Q1	SOIC-8	1050AQ	SN65HVD1050AQDRQ1 (reel)

(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI web site at www.ti.com.
(2) Package drawings, thermal data, and symbolization are available at www.ti.com/packaging.

ABSOLUTE MAXIMUM RATINGS(1)

		UNIT
V_{CC}	Supply voltage range(2)	–0.3 V to 7 V
	Voltage range at any bus terminal (CANH, CANL, V_{ref})	–27 V to 40 V
I_O	Receiver output current	20 mA
V_I	Voltage input range, ISO 7637 transient pulse(3) (CANH, CANL)	–150 V to 100 V
V_I	Voltage input range (TXD, S)	–0.5 V to 6 V
T_J	Junction temperature range	–40°C to 150°C

(1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
(2) All voltage values, except differential I/O bus voltages, are with respect to network ground terminal.
(3) Tested in accordance with ISO 7637 test pulses 1, 2, 3a, 3b per IBEE system level test (Pulse 1 = –100 V, Pulse 2 = 100 V, Pulse 3a = –150 V, Pulse 3b = 100 V). If dc may be coupled with ac transients, externally protect the bus pins within the absolute maximum voltage range at any bus terminal. This device has been tested with dc bus shorts to +40V with leading common-mode chokes. If common-mode chokes are used in the system and the bus lines may be shorted to dc, ensure that the choke type and value in combination with the node termination and shorting voltage either will not create inductive flyback outside of voltage maximum specification or use an external transient-suppression circuit to protect the transceiver from the inductive transients.

ELECTROSTATIC DISCHARGE PROTECTION

PARAMETER	TEST CONDITIONS		UNIT
Electrostatic discharge (1)	Human-Body Model(2)	CANH and CANL bus pins(3)	±12 kV
		V_{ref} pin(4)	±10 kV
		All pins	±4 kV
	Charged-Device Model(5)	All pins	±1.5 kV
	Machine Model(6)		±200 V

(1) All typical values at 25°C.
(2) Tested in accordance JEDEC Standard 22, Test Method A114E.
(3) Test method based upon JEDEC Standard 22 Test Method A114E, CANH and CANL bus pins stressed with respect to each other and GND.
(4) Test method based upon JEDEC Standard 22 Test Method A114E, V_{ref} pin stressed with respect to GND.
(5) Tested in accordance JEDEC Standard 22, Test Method C101C.
(6) Tested in accordance JEDEC Standard 22, Test Method A115A.

RECOMMENDED OPERATING CONDITIONS

			MIN	MAX	UNIT
V_{CC}	Supply voltage		4.75	5.25	V
V_I or V_{IC}	Voltage at any bus terminal (separately or common mode)		–12	12	V
V_{IH}	High-level input voltage	TXD, S	2	5.25	V
V_{IL}	Low-level input voltage	TXD, S	0	0.8	V
V_{ID}	Differential input voltage		–6	6	V
I_{OH}	High-level output current	Driver	–70		mA
		Receiver	–2		
I_{OL}	Low-level output current	Driver		70	mA
		Receiver		2	
T_A	Operating free-air temperature range	See Thermal Characteristics table	–40	125	°C

SUPPLY CURRENT

over recommended operating conditions, T_A = –40 to 125°C (unless otherwise noted)

PARAMETER			TEST CONDITIONS	MIN	TYP(1)	MAX	UNIT
I_{CC}	5-V supply current	Silent mode	S at V_{CC}, V_I = V_{CC}		6	10	mA
		Dominant	V_I = 0 V, 60-Ω load, S at 0 V		50	70	
		Recessive	V_I = V_{CC}, No load, S at 0 V		6	10	

(1) All typical values are at 25°C with a 5-V supply.

DEVICE SWITCHING CHARACTERISTICS

over recommended operating conditions, T_A = –40 to 125°C (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	MAX	UNIT
$t_{d(LOOP1)}$	Total loop delay, driver input to receiver output, recessive to dominant	S at 0 V, See Figure 9	90	230	ns
$t_{d(LOOP2)}$	Total loop delay, driver input to receiver output, dominant to recessive	S at 0 V, See Figure 9	90	230	ns

DRIVER ELECTRICAL CHARACTERISTICS

over recommended operating conditions, T_A = –40 to 125°C (unless otherwise noted)

PARAMETER			TEST CONDITIONS	MIN	TYP(1)	MAX	UNIT
$V_{O(D)}$	Bus output voltage (dominant)	CANH	V_I = 0 V, S at 0 V, R_L = 60 Ω, See Figure 1 and Figure 2	2.9	3.4	4.5	V
		CANL		0.8		1.5	
$V_{O(R)}$	Bus output voltage (recessive)		V_I = 3 V, S at 0 V, R_L = 60 Ω, See Figure 1 and Figure 2	2	2.3	3	V
$V_{OD(D)}$	Differential output voltage (dominant)		V_I = 0 V, R_L = 60 Ω, S at 0 V, See Figure 1, Figure 2, and Figure 3	1.5		3	V
			V_I = 0 V, R_L = 45 Ω, S at 0 V, See Figure 1, Figure 2, and Figure 3	1.4		3	V
$V_{OD(R)}$	Differential output voltage (recessive)		V_I = 3 V, S at 0 V, See Figure 1 and Figure 2	–0.012		0.012	V
			V_I = 3 V, S at 0 V, No Load	–0.5		0.05	
$V_{OC(ss)}$	Steady state common-mode output voltage		S at 0 V, Figure 8	2	2.3	3	V
$\Delta V_{OC(ss)}$	Change in steady-state common-mode output voltage				30		mV
I_{IH}	High-level input current, TXD input		V_I at V_{CC}	–2		2	µA
I_{IL}	Low-level input current, TXD input		V_I at 0 V	–50		–10	
$I_{O(off)}$	Power-off TXD output current		V_{CC} at 0 V, TXD at 5 V			1	
$I_{OS(ss)}$	Short-circuit steady-state output current		V_{CANH} = –12 V, CANL open, See Figure 11	–105	–72		mA
			V_{CANH} = 12 V, CANL open, See Figure 11		0.36	1	
			V_{CANL} = –12 V, CANH open, See Figure 11	–1	–0.5		
			V_{CANL} = 12 V, CANH open, See Figure 11		71	105	
C_O	Output capacitance		See receiver input capacitance				

(1) All typical values are at 25°C with a 5-V supply.

DRIVER SWITCHING CHARACTERISTICS

oover recommended operating conditions, T_A = –40 to 125°C (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP(1)	MAX	UNIT
t_{PLH}	Propagation delay time, low-to-high level output	S at 0 V, See Figure 4	25	65	120	ns
t_{PHL}	Propagation delay time, high-to-low level output	S at 0 V, See Figure 4	25	45	120	ns
t_r	Differential output signal rise time	S at 0 V, See Figure 4		25		ns
t_f	Differential output signal fall time	S at 0 V, See Figure 4		50		ns
t_{en}	Enable time from silent mode to dominant	See Figure 7			1	µs
$t_{(dom)}$	Dominant time out(2)	↓V_I, See Figure 10	300	450	700	µs

(1) All typical values are at 25°C with a 5-V supply.
(2) The TXD dominant time out (t(dom)) will disable the driver of the transceiver once the TXD has been dominant longer than $t_{(dom)}$ which will release the bus lines to recessive preventing a local failure from locking the bus dominant. The driver may only transmit dominant again after TXD has been returned HIGH (recessive). While this protects the bus from local faults locking the bus dominant it will limit the minimum data rate possible. The CAN protocol allows a maximum of eleven successive dominant bits (on TXD) for the worst case where five successive dominant bits are followed immediately by an error frame. This along with the $t_{(dom)}$ minimum will limit the minimum bit rate. The minimum bit rate may be calculated by: Minimum Bit Rate = 11/ $t_{(dom)}$ = = 11 bits / 300µs = 37 kbps.

RECEIVER ELECTRICAL CHARACTERISTICS

over recommended operating conditions, T_A = –40 to 125°C (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP(1)	MAX	UNIT
V_{IT+}	Positive-going input threshold voltage	S at 0 V, See Table 1		800	900	mV
$V_{IT–}$	Negative-going input threshold voltage	S at 0 V, See Table 1	500	650		mV
V_{hys}	Hysteresis voltage (V_{IT+} – $V_{IT–}$)		100	125		mV
V_{OH}	High-level output voltage	I_O = –2 mA, See Figure 6	4	4.6		V
V_{OL}	Low-level output voltage	I_O = 2 mA, See Figure 6		0.2	0.4	V
$I_{I(off)}$	Power-off bus input current	CANH or CANL = 5 V, Other pin at 0 V, V_{CC} at 0 V, TXD at 0 V		165	250	µA
$I_{O(off)}$	Power-off RXD leakage current	V_{CC} at 0 V, RXD at 5 V			20	µA
C_I	Input capacitance to ground (CANH or CANL)	TXD at 3 V, V_I = 0.4 sin (4E6πt) + 2.5 V		13		pF
C_{ID}	Differential input capacitance	TXD at 3 V, V_I = 0.4 sin (4E6πt)		6		pF
R_{ID}	Differential input resistance	TXD at 3 V, S at 0 V	30		80	kΩ
R_{IN}	Input resistance (CANH or CANL)	TXD at 3 V, S at 0 V	15	30	40	kΩ
$R_{I(m)}$	Input resistance matching [1 – ($R_{IN\ (CANH)}$ / $R_{IN\ (CANL)}$)] × 100%	$V_{(CANH)}$ = $V_{(CANL)}$	–3	0	3	%

(1) All typical values are at 25°C with a 5-V supply.

RECEIVER SWITCHING CHARACTERISTICS

over recommended operating conditions, T_A = –40 to 125°C (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP(1)	MAX	UNIT
t_{PLH}	Propagation delay time, low-to-high-level output	S at 0 V or V_{CC}, See Figure 6	60	100	130	ns
t_{PHL}	Propagation delay time, high-to-low-level output		45	70	130	ns
t_r	Output signal rise time			8		ns
t_f	Output signal fall time			8		ns

(1) All typical values are at 25°C with a 5-V supply.

S PIN CHARACTERISTICS

over recommended operating conditions, T_A = –40 to 125°C (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP(1)	MAX	UNIT
I_{IH}	High level input current	S at 2 V	20	40	70	µA
I_{IL}	Low level input current	S at 0.8 V	5	20	30	µA

(1) All typical values are at 25°C with a 5-V supply.

VREF PIN CHARACTERISTICS

over recommended operating conditions, T_A = –40 to 125°C (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP(1)	MAX	UNIT
V_O	Reference output voltage	–50 µA < I_O < 50 µA	0.4 V_{CC}	0.5 V_{CC}	0.6 V_{CC}	V

(1) All typical values are at 25°C with a 5-V supply.

THERMAL CHARACTERISTICS

over recommended operating conditions, T_A = –40 to 125°C (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
θ_{JA}	Junction-to-air thermal resistance(1)	Low-K thermal resistance(2)		211		°C/W
		High-K thermal resistance(2)		131		
θ_{JB}	Junction-to-board thermal resistance			53		°C/W
θ_{JC}	Junction-to-case thermal resistance			79		°C/W
P_D	Average power dissipation	V_{CC} = 5 V, T_J = 27°C, R_L = 60 Ω, S at 0 V, Input to TXD at 500 kHz, 50% duty cycle square wave, CL at RXD = 15 pF		112		mW
		V_{CC} = 5.5 V, T_J = 130°C, R_L = 45 Ω, S at 0 V, Input to TXD at 500 kHz, 50% duty cycle square wave, CL at RXD = 15 pF			170	
	Thermal shutdown temperature			190		°C

(1) The junction temperature (T_J) is calculated using the following $T_J = T_A + (P_D * \theta_{JA})$.
(2) Tested in accordance with the Low-K (EIA/JESD51-3) or High-K (EIA/JESD51-7) thermal metric definitions for leaded surface-mount packages.

FUNCTION TABLES

DRIVER(1)

INPUTS		OUTPUTS		BUS STATE
TXD	S	CANH	CANL	
L	L or Open	H	L	Dominant
H	X	Z	Z	Recessive
Open	X	Z	Z	Recessive
X	H	Z	Z	Recessive

(1) H = high level, L = low level, X = irrelevant, ? = indeterminate, Z = high impedance

RECEIVER(1)

DIFFERENTIAL INPUTS V_{ID} = V(CANH) – V(CANL)	OUTPUT RXD	BUS STATE
$V_{ID} \geq 0.9$ V	L	Dominant
0.5 V < V_{ID} < 0.9 V	?	?
$V_{ID} \leq 0.5$ V	H	Recessive
Open	H	Recessive

(1) H = high level, L = low level, X = irrelevant, ? = indeterminate, Z = high impedance

PARAMETER MEASUREMENT INFORMATION

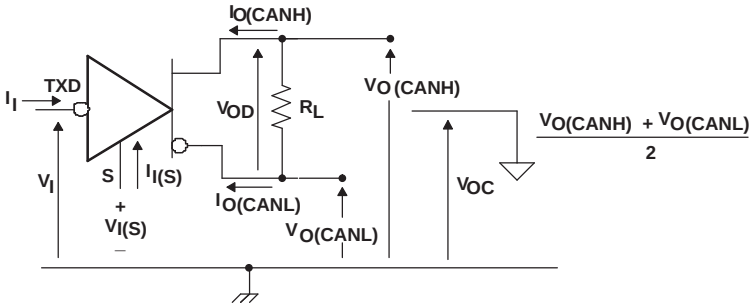


Figure 1. Driver Voltage, Current, and Test Definition

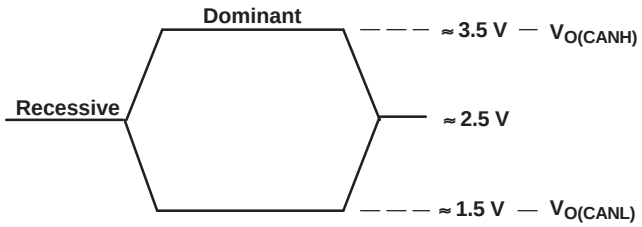


Figure 2. Bus Logic State Voltage Definitions

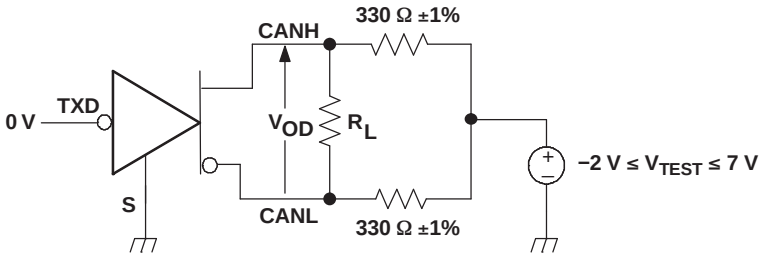


Figure 3. Driver V_{OD} Test Circuit

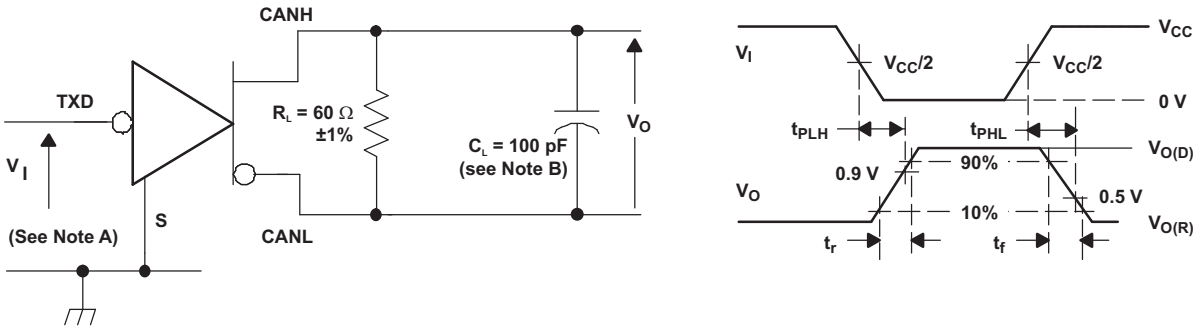


Figure 4. Driver Test Circuit and Voltage Waveforms

PARAMETER MEASUREMENT INFORMATION (continued)

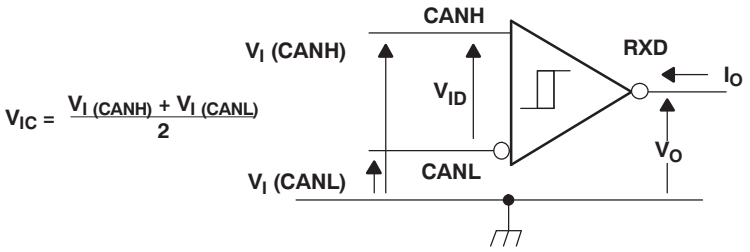
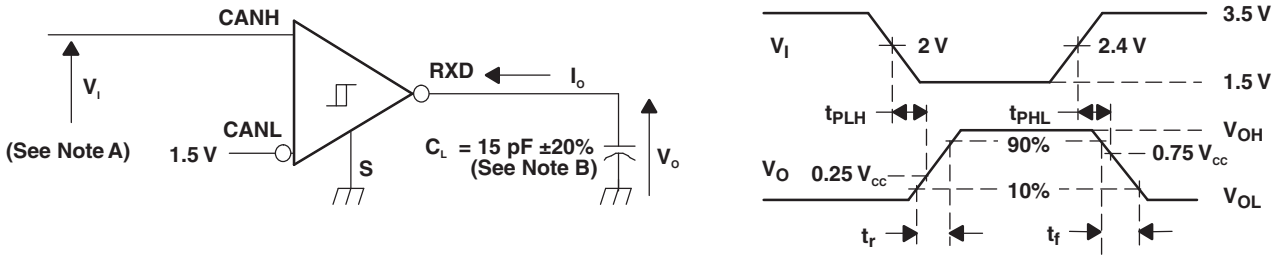


Figure 5. Receiver Voltage and Current Definitions



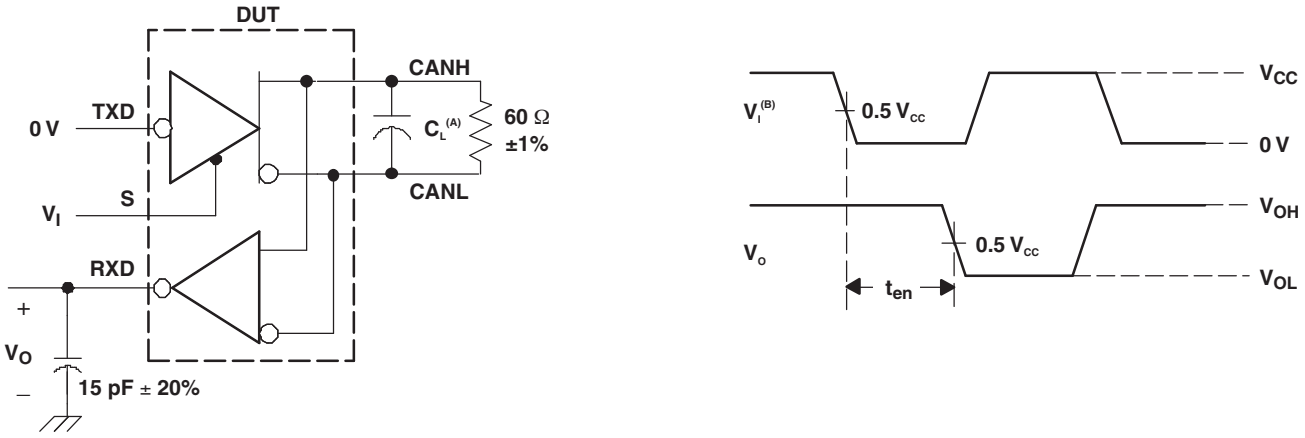
A. The input pulse is supplied by a generator having the following characteristics: PRR ≤ 125 kHz, 50% duty cycle, t_r ≤ 6 ns, t_f ≤ 6 ns, Z_O = 50 Ω.

B. C_L includes instrumentation and fixture capacitance within ±20%.

Figure 6. Receiver Test Circuit and Voltage Waveforms

Table 1. Differential Input Voltage Threshold Test

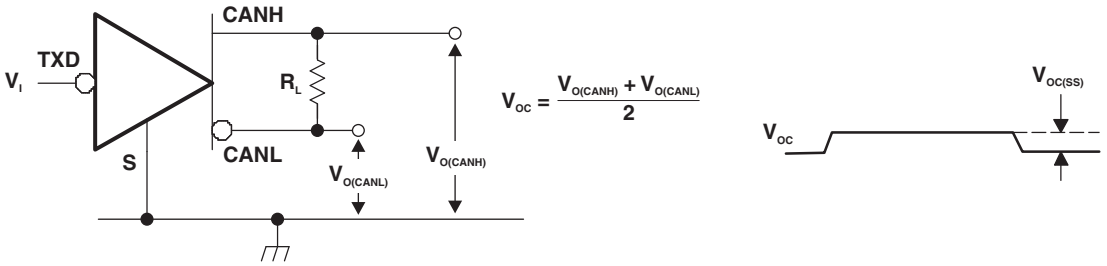
INPUT			OUTPUT	
V_{CANH}	V_{CANL}	$\lvert V_{ID}\rvert$	R	
–11.1 V	–12 V	900 mV	L	V_{OL}
12 V	11.1 V	900 mV	L	
–6 V	–12 V	6 V	L	
12 V	6 V	6 V	L	
–11.5 V	–12 V	500 mV	H	V_{OH}
12 V	11.5 V	500 mV	H	
–12 V	–6 V	6 V	H	
6 V	12 V	6 V	H	
Open	Open	X	H	



A. C_L = 100 pF and includes instrumentation and fixture capacitance within ±20%.

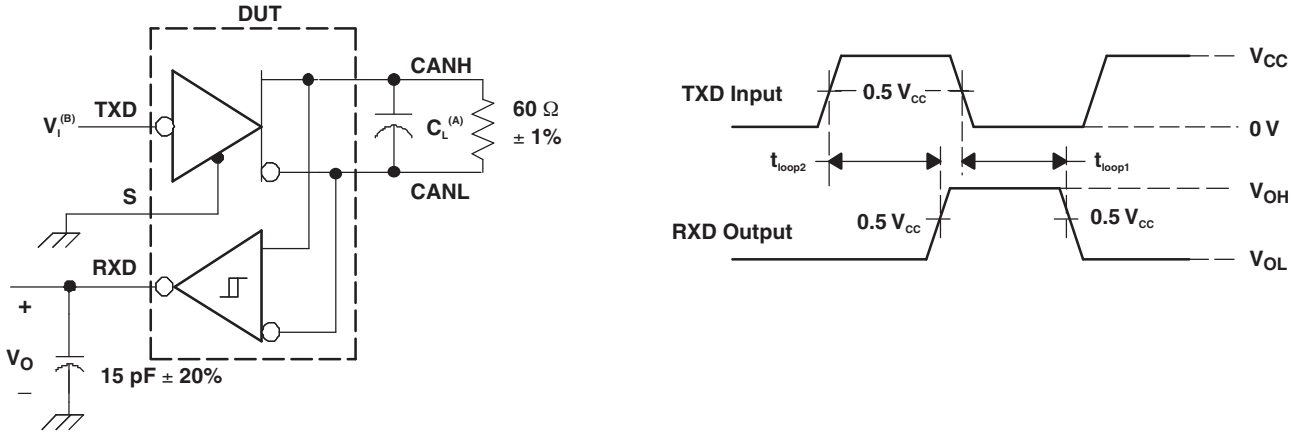
B. All V_I input pulses are supplied by a generator having the following characteristics: t_r or t_f ≤ 6 ns, pulse repetition rate (PRR) = 125 kHz, 50% duty cycle.

Figure 7. t_{en} Test Circuit and Waveforms



NOTE: All V_I input pulses are from 0 V to V_{CC} and supplied by a generator having the following characteristics: t_r or t_f ≤ 6 ns, pulse repetition rate (PRR) = 125 kHz, 50% duty cycle.

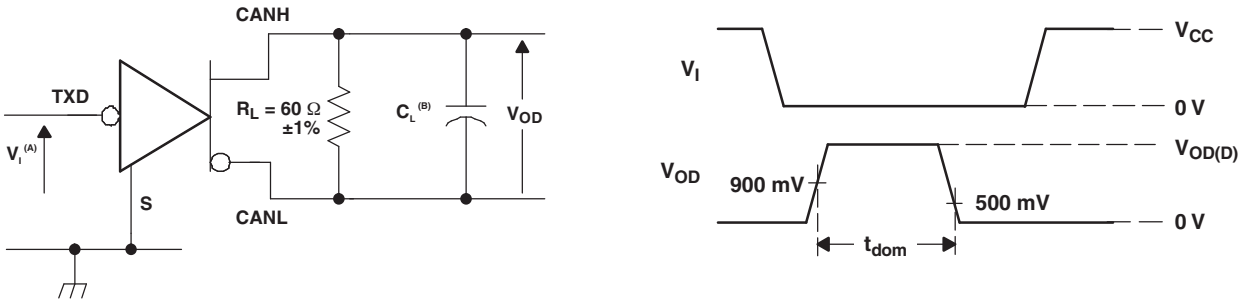
Figure 8. Common-Mode Output Voltage Test and Waveforms



A. C_L = 100 pF and includes instrumentation and fixture capacitance within ±20%.

B. All V_I input pulses are from 0 V to V_{CC} and supplied by a generator having the following characteristics: t_r or t_f ≤ 6 ns, pulse repetition rate (PRR) = 125 kHz, 50% duty cycle.

Figure 9. $t_{(LOOP)}$ Test Circuit and Waveforms



A. All V_I input pulses are from 0 V to V_{CC} and supplied by a generator having the following characteristics: t_r or t_f ≤ 6 ns, pulse repetition rate (PRR) = 500 Hz, 50% duty cycle.

B. C_L = 100 pF includes instrumentation and fixture capacitance within ±20%.

Figure 10. Dominant Time-Out Test Circuit and Waveforms

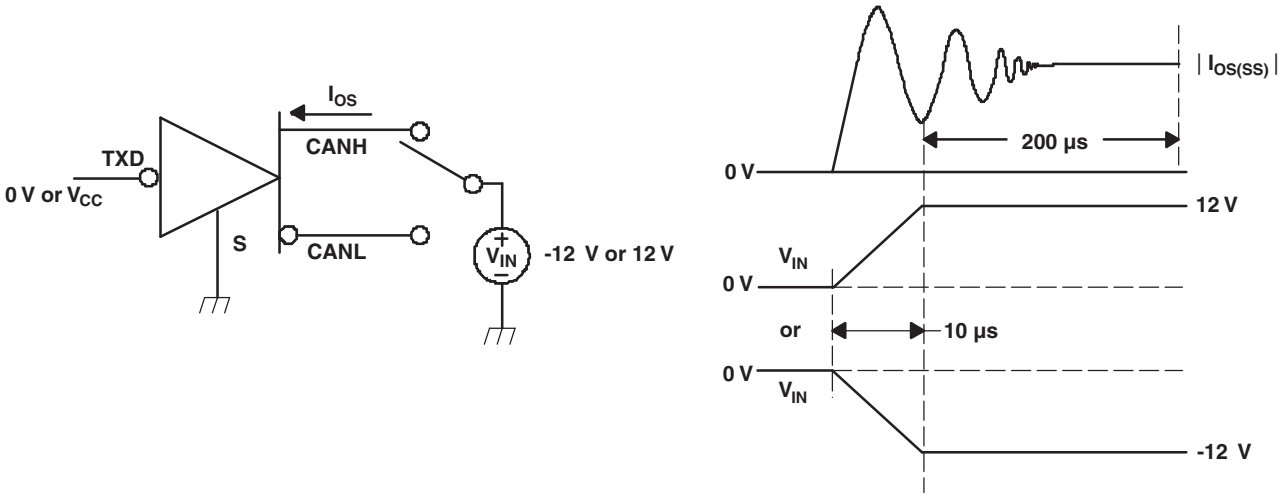


Figure 11. Driver Short-Circuit Current Test and Waveforms

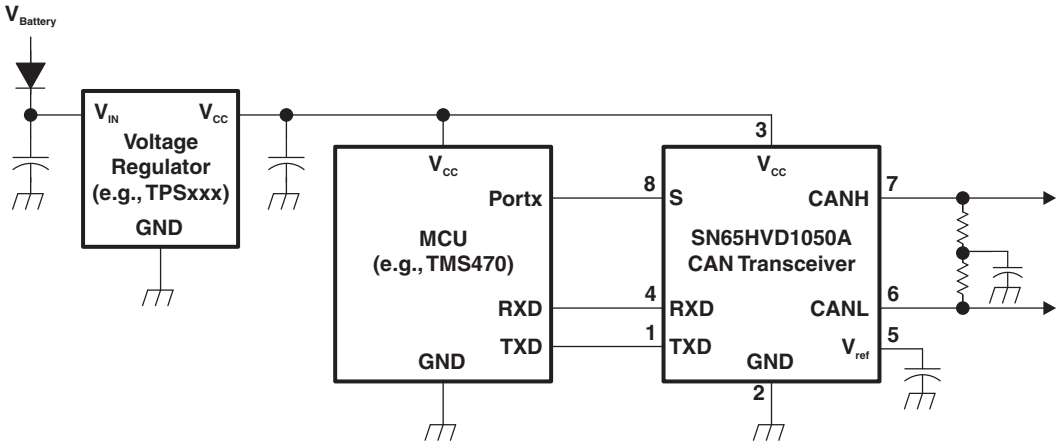
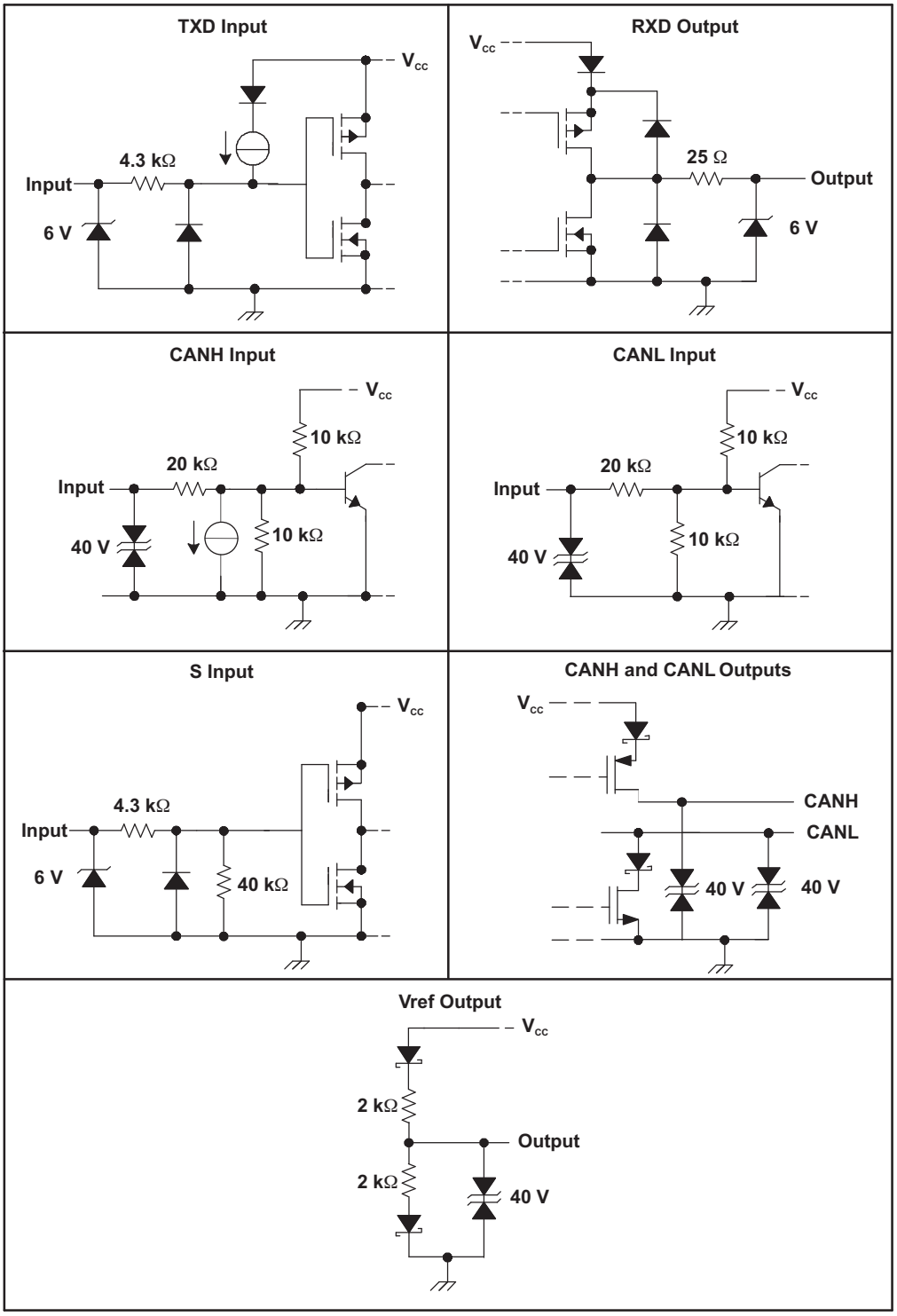
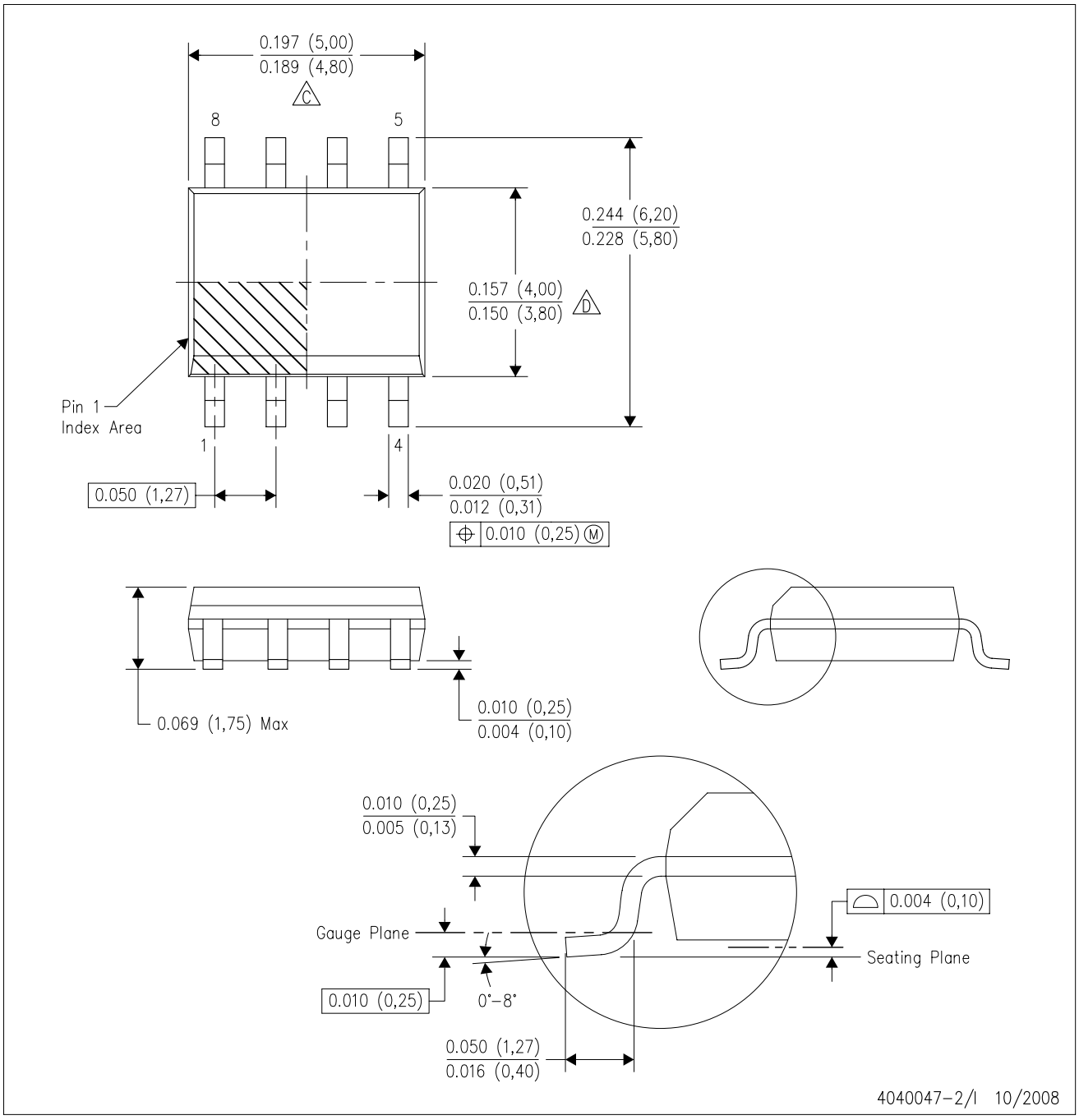


Figure 12. Typical Application

Equivalent Input and Output Schematic Diagrams



D (R–PDSO–G8) PLASTIC SMALL–OUTLINE PACKAGE



NOTES:
A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.
C. Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 (0,15) per end.
D. Body width does not include interlead flash. Interlead flash shall not exceed .017 (0,43) per side.
E. Reference JEDEC MS–012 variation AA.

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